### Lecture 3

## Circular shifting: Delaying



## Circular shifting: Advancing



## Circular Folding



## Circular Symmetry

e. Cizwlazly eve  $\alpha$  (n) =  $\left\{$ circulacly odd  $\Omega$  $O((n)=\frac{1}{2}, -3, 0)$  $\overline{3}$ 

 $x_2(n) = \{y_1^3, z_1^2\}$  $1_{2}(3)=2$  $x_{2}$  $(0)$  $x_{1}$ メび こう

# Summary: Circular Operations



- Methods of Circular Convolution
- Generally, there are two methods, which are adopted to perform circular convolution and they are −
- Concentric circle method,
- Matrix multiplication method.
- **Concentric Circle Method**
- Let x1(n)x1(n) and x2(n)x2(n) be two given sequences. The steps followed for circular convolution of  $x1(n)x1(n)$  and  $x2(n)x2(n)$  are
- Take two concentric circles. Plot N samples of  $x1(n)x1(n)$  on the circumference of the outer circle maintainingequaldistancesuccessivepointsmaintainingequaldistancesuccessivepoints in anti-clockwise direction.
- For plotting x2(n)x2(n), plot N samples of x2(n)x2(n) in clockwise direction on the inner circle, starting sample placed at the same point as 0<sup>th</sup> sample of  $x1(n)x1(n)$
- Multiply corresponding samples on the two circles and add them to get output.
- Rotate the inner circle anti-clockwise with one sample at a time.
- **Matrix Multiplication Method**
- Matrix method represents the two given sequence x1(n)x1(n) and x2(n)x2(n) in matrix form.
- One of the given sequences is repeated via circular shift of one sample at a time to form a N X N matrix.
- The other sequence is represented as column matrix.
- The multiplication of two matrices give the result of circular convolution.

# **Circular Convolution**

• Circular convolution is defined by:

$$
y_C[n] = \sum_{m=0}^{N-1} g[m]h[(n-m)_N], \quad 0 \le n \le N-1
$$

• N-point circular convolution is denoted as,

 $y[n] = g[n] \otimes h[n]$ 

• The circular convolution is commutative, i.e

 $g[n] \otimes h[n] = h[n] \otimes g[n]$ 

#### **Circular Convolution: Method 1**



#### **Circular Convolution: Graphical Method**

 $x(n) = \{2, 0, 3, -1\}$  $h(n) = \{10, 20, 30, 40\}$ 

**Reversed Signal 2** 

Product



#### **Circular Convolution: Graphical Method**





#### **Circular Convolution: Graphical Method**



#### **Circular Convolution:-Graphical Method**



# Circular Convolution: Method 2



### Circular convolution: Matrix Method



### Circular Convolution: Matrix Method

 $4\quad 2\quad 2\quad 3$ 3 4 2 2  $\begin{array}{c} \hline \end{array}$  $2342$  $|3$  $y(2)$  $2\ 2\ 3\ 4$ 



Example - Consider the two length-4 sequences repeated below for convenience:



• The two 4-point DFTs can also be computed as

$$
\begin{bmatrix} G[0] \\ G[1] \\ G[2] \\ G[3] \end{bmatrix} = \mathbf{D}_4 \begin{bmatrix} g[0] \\ g[1] \\ g[2] \\ g[3] \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} H[0] \\ H[1] \\ H[1] \\ H[2] \end{bmatrix} = \mathbf{D}_4 \begin{bmatrix} h[0] \\ h[1] \\ h[2] \\ h[2] \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} H[3] \\ H[3] \end{bmatrix}
$$

The two 4-point DFTs can also be computed using the matrix relation given earlier



$$
\mathbf{Y}_{C}[k] = \begin{bmatrix} Y_{C}[0] \\ Y_{C}[1] \\ Y_{C}[2] \\ Y_{C}[3] \end{bmatrix} = \begin{bmatrix} G[0]H[0] \\ G[1]H[1] \\ G[2]H[2] \\ G[3]H[3] \end{bmatrix} =
$$



• A 4-point IDFT of  $Y_c[k]$  yields



• A 4-point IDFT of  $Y_c[k]$  yields













 $N-1$  $N$ -point circular  $\sum g[m]h[\langle n-m \rangle_N]$  $G[k]H[k]$ convolution  $m=0$ 

$$
\mathbf{x(k)} = \{4, -2j, 0, j\}
$$
  
\n
$$
H(k) = \{3, 1 - 2j, -1, 1 + 2j\}
$$
  
\n
$$
Y(k) = X(k)H(k)
$$
  
\n
$$
Y(k) = \{4, -2j, 0, j\}, \{3, 1 - 2j, -1, 1 + 2j\}
$$

$$
Y(k) = \{12, -2j - 4, 0, j - 2\}
$$

# **Properties of DFT**

